An investigation into the depth and time dependent behavior of UV cured 3D ink jet printed objects

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An ultra-violet (UV) curable ink jet 3D printed material was characterized by an inverse finite element modeling (IFEM) technique employing a nonlinear viscoelastic–viscoplastic (NVEVP) material constitutive model; this methodology was compared directly with nanoindentation tests. The printed UV cured ink jet material properties were found to be z-depth dependent owing to the sequential layer-by-layer deposition approach. With further post-UV curing, the z-depth dependence was weakened but properties at all depths were influenced by the duration of UV exposure, indicating that none of the materials within the samples had reached full cure during the 3D printing process. Effects due to the proximity of an indentation to the 3D printed material material-sample fixing interface, and the different mounting material, in a test sample were examined by direct 3D finite element simulation and shown to be insignificant for experiments performed at a distance greater than 20 μm from the interface.

I. INTRODUCTION

Additive manufacturing (AM) or 3D printing is the technology of building three-dimensional objects layer-by-layer using computer-aided designs (CAD). It is capable of fabricating complex three-dimensional objects, which cannot be produced using conventional manufacturing techniques. It consists of several classes of processes, including extrusion, powder bed fusion, vat photopolymerization, and importantly, material jetting (MJ), based on ink jet based techniques. This latter process is significant, since it is one of the most promising routes to AM based multi-material (MFAM) production. Both extrusion and MJ methods have been used to develop MFAM, with extrusion showing interesting developments in terms of biological material scaffolds in tissue engineering amongst other applications. The fundamental difference between extrusion and MJ is the mode of delivery, where extrusion is capable of delivering relatively highly loaded or higher molecular weight materials but at lower resolution than MJ. Should MFAM be realized, it will lead to the production of new multifunctional products, including those in the electronics, bio-printing, and pharmaceutical industries. One mode of ink jet printing is reactive ink jet (RIJ). RIJ involves the deposition of one or more liquid raw materials onto the same location, after which a chemical interaction is activated, producing a new material in situ to the manufacturing process. One common method is to use materials that are able to crosslink under the application of ultra-violet (UV) light. Commercial machines are now available where the UV source is in line with the printing head, leading to the creation of material on a layer-by-layer basis. In this regard, there are similarities to stereolithography (SLA), which also relies on UV based solidification mechanisms. This latter-layer by-layer synthesis approach however, whilst it has advantages in being able to readily access forms not achievable by traditional manufacturing methods, is not well understood, particularly in relation to the distribution of material properties, both temporally and spatially. Recently it has been shown that mechanical testing methods can be combined with finite element (FE) based solid mechanical models to create an inverse FE method (IFEM) for characterizing complex material properties. This method is particularly useful when combined with nanoindentation as the test enables the spatial distribution of properties to be investigated whilst the IFEM enables access to material models not available in the standard forward analysis of nanoindentation data. This technique has been described previously by the authors in the analysis of 3D ink jet based printed objects to identify spatial variation in properties. All methods and applications using the IFEM technique require selection of the right material constitutive model since without it, it is not possible to describe the mechanical behavior of the material in question. In Ref. 28, four different material constitutive models were used: linear viscoelastic (VE), nonlinear viscoelastic (NVE), viscoelastic–viscoplastic (VEVP), and nonlinear viscoelastic–viscoplastic (NVEVP). The work showed that the NVEVP material model offers the best approximation for the material used in that study.
What was also evident from this work were the strong spatially varying properties in the printed materials and as a consequence, it was proposed that the time and spatial dependence of these materials should be examined. In this paper, the IFEM based method will be used to investigate the time and spatially varying material properties of a 3D ink jet printed object. The methodology for preparing samples and their analysis will be presented first, followed by an analysis of the variation of mechanical properties, both with and without post-curing. Finally an assessment will be made of possible errors that can be introduced into the analysis by the presence of fixing agents and property gradients during the experimental testing.

II. EXPERIMENTAL STUDY

A. Samples preparation and nanoindentation

All materials within this work were printed using a Stratasys Objet Connex 260 3-D printer system. The ink used was VeroClear Fullcure 810 (Stratasys Ltd.). This ink is available in the liquid state and then cured to form a solid through exposure to suitable UV light. To prepare samples, the inks were printed into 40 × 10 × 5 mm³ rectangular sections; the solid samples were then chopped into small cuboid pieces using a hand saw. Initial polishing was performed on each piece to remove a layer of material on each chopped surface, to avoid the possible detection of mechanical hardening caused by chopping. These small pieces were mounted on Epoxy resin, using Epoxy hardener as a crosslink agent, at a 15:2 volume ratio in a cylindrical sample mold kept at room temperature. The mounted sample was allowed to harden for at least 8 hours which was followed by grinding and polishing, to produce a mountable sample ready for nanoindentation. Figure 1(a) shows an example of one of these samples. It is a cylinder with both the diameter and height of around 30 mm, containing several VeroClear cuboid solids within the sample. Each surface was clearly marked to ensure the correct orientation was achieved and was observable under the microscope of the indentation machine [Fig. 1(a)].

Nanoindentation tests were conducted on a NanoTest600 instrument (Micro Materials Limited). The machine is housed in a polymethyl methacrylate (PMMA) enclosure to separate the instrument from environmental perturbations. In our study, the loading pattern was fixed and a typical depth versus time curve was obtained [Figs. 1(c) and 1(d)]. The loading time was set at 50 s, during which the indentation load linearly increased from zero to a maximum, after which the indentation load was maintained for 500 s to allow the material to creep. In the last 50 s, the indentation load was linearly decreased from maximum to zero, resulting in the recovery of elastic deformation. The aim of the IFEM is to extract the optimal local material property parameters from the depth–time curve under a given load for a specified material constitutive model.

B. Post-curing UV illumination conditions

To investigate any material property changes after production, nanoindentation tests with post-cured samples were also performed. To achieve this, the samples were exposed to a UV light source in a test chamber. A Q-Sun UV oven xenon test chamber was used for this purpose, which allowed the exposure of the sample with UV light at a wave length of 340 nm at a prescribed level of 0.68 W/m² and temperature of 50 °C. The prepared VeroClear cuboids were exposed to UV light between 2.5 min and 40 h. Control experiments were performed on samples sealed in the aluminum foil. The samples and
their controls were mounted with epofix resin at room
temperature to form nanoindentation samples ready for
sanding and polishing. When not under testing, samples
were stored within an air-conditioned environment,
wrapped with dry tissue paper, and covered with the
aluminum foil to avoid further UV exposure.

Figure 2 shows the schematic experimental protocols
used in indentation tests for samples without post-curing
[Figs. 2(a) and 2(b)] and for samples with post-curing
[Fig. 2(c)]. The maximum indentation load was given
by two values, first at 50 mN for the samples with UV
post-curing up to and equal to 60 min, and at 75 mN for
post-curing greater than 60 min, to allow maximal
indentation depth at the same level for all samples, and
thus keeping the signal to noise ratio and surface
roughness effects at the same level for all samples.

III. RESULTS

A series of experiments were performed to determine
the $x$ and $z$ dependence of the material properties and
the effect of additional UV curing post-deposition.
Table I shows the experiments performed and the relevant
properties and conditions.

A. Material property variation following 3D printing

The dependence of material properties on the $x$- and
$z$-position was first examined by conducting a $6 \times 6$
indentation array test on a sample cross section [Fig. 2(b)]
mapping along both the $x$ and $z$ directions. Figure 3 shows
the maximum indentation depth, hardness, and reduced
modulus for various $x$ locations and $z$-depths. It can be
seen that in the $x$ direction, the properties were broadly
constant but that there is a large variation in all properties
as a function of depth. The legend in the figure shows the
distance of indentation location to the top surface of the
sample and it can be seen that closer to the top surface,
the maximum indentation depth increases and both the
hardness and reduced modulus decrease. This indicates
that a greater degree of cure has been experienced by the
material at a larger depth from the top surface, which is
explored in more detail below.

It is hypothesized that the observed $z$-depth depen-
dency in the material properties is closely related to the
material manufacturing procedure deployed in the MJ
process. This is emphasized by the appearance of clear
interfaces between layers as seen in the polished cross
section in Fig. 4(a). Figure 4(b) shows the same surface
after indentation and it can be seen that there are larger
and more defined indent closer to the top surface of the
sample, reinforcing the data in Fig. 3 and the observed
trend that the layers nearer the top surface are softer.
However, the layers are no longer visible after post-
curing with UV light. The VeroClear ink was jetted layer-
by-layer using the Objet260 Connex system. The modus
operandi of the system is to print material which is then
almost immediately exposed to UV light which initiates
a crosslinking reaction in the polymer. Since VeroClear
has a degree of transparency in the UV region used to
initiate the crosslinking reaction, when a subsequent layer
of material is printed, the initial layer of the material will
be exposed to further UV irradiation albeit to a lesser
extent due to absorption of some of the incident light by
the second layer. It is thought, however, that this multiple
pass of UV light will result in further cross-linking of
previous layers resulting in a degree of cross-linking

<table>
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<th>Nanoindentation array test</th>
<th>Relevant properties</th>
<th>Test surfaces</th>
<th>Figure</th>
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<td>Cross section</td>
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<td>UV post-curing</td>
<td>Cross section</td>
<td>Figure 9</td>
<td>50 &amp; 75</td>
</tr>
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</table>

![Image](image_url)
strongly dependent on \( z \). To test this idea of depth dependent cross-linking, an experiment was performed to examine the degree of cross-linking using a Fourier transform near infrared (FTIR) spectrometer (PerkinElmer Inc.). The degree of cross-linking at the top, middle, and bottom locations (0, 0.5, and 3 mm from the top surface, respectively) on a sample cross section was compared using a field of view of \( 1 \text{ mm}^2 \), which although not able to provide the quantitative analysis of the chemistry with the resolution over which depth changes are likely to occur, will indicate coarse changes in chemistry. Figure 5 shows the absorbance due to C=C bonds at the top, middle, and bottom locations [Fig. 5(a)] on the sample cross section, with the bottom region showing significantly lower absorbance, indicating a greater degree of cross-linking in layers deposited earlier. This behavior can be captured in a simple, discrete model of absorption as follows.
The initial concentration of a reactant (such as readily available photo-initiator available for interaction with a photon) is \( c_0 \), and the UV light intensity incident upon the uppermost layer is \( I_0 \). Following the illumination of the sample with UV light for a duration of \( \Delta t \), a chemical reaction occurs and a concentration change in the current printing layer will result, giving

\[
\Delta c_0 = -kI_0 c_0 \Delta t \quad ,
\]

where \( k \) is a constant of proportionality that relates the change in concentration to the state of the illuminating light and the material condition, and \( \Delta c_0 \) is the change of concentration due to the first illuminating. Therefore, the concentration of reactant, \( c_1 \), immediately after the first pass, in layer 1, is given by

\[
c_1 = c_0 + \Delta c_0 = c_0 (1 - kI_0 \Delta t) \quad .
\]

When another layer is deposited onto the already printed first layer, the UV light intensity incident on the first printed layer (now the bottom layer) is \( I_1 = \alpha I_0 \) where \( \alpha \approx 1 \) as a result of absorption of the material when passing through the current printing layer, leading to a change in the concentration of
\[ \Delta c_1 = -k_1 c_1 \Delta t, \quad (3) \]

so that when the second deposition is finished, the concentration in the first printed layer becomes

\[ c_2 = c_0 \left( 1 - k_1 c_1 \Delta t \right) \left( 1 - k_0 c_0 \Delta t \right), \quad (4) \]

where the superscripts reflect the changing conditions of each layer, leading to possible variation in absorption.

FIG. 6. (a) The maximum depth achieved with 50 mN indentation load, and the indentations and locations that will be used in IFEM, marked by crosses. (b) and depth versus time curves used in IFEM. The curves correspond to the crosses in (a).

FIG. 7. Typical material parameters of RIJ printed VeroClear achieved by IFEM: (a) Instantaneous modulus as a function of \( z \), determined using the NVEVP material constitutive models, (b) nonlinear coefficients obtained by fitting the NVEVP model and subsequently Eq. (6), (c) initial yield stress, and (d) the viscoplastic parameter, \( \eta \), as a function of \( z \).
coefficients. Generally, when the nth layer printing is finished, the resultant concentration of the first printed layer is

$$c_n = c_0 \left(1 - kI_0 x^0 \Delta t\right) \left(1 - kI_0 x^1 \Delta t\right) \cdots \left(1 - kI_0 x^{n-1} \Delta t\right).$$

(5)

In this work, it is assumed that the material interacts only weakly with the incident radiation, allowing us to simplify to one value of $x$ for all layers of the material. Plotting Eq. (5) and comparing it with an exponentially decaying function showed good agreement, allowing further simplification and parameterization of the behavior with phenomenological constants. Mechanical properties are known to be linked to the degree of completion of the cross-linking process, thus it is reasonable to characterize these using a similar form of equation. Therefore, it is assumed that all properties will show a depth dependency of the form

$$R = R_0 \left[1 - \exp\left(-\frac{Z}{Z_0}\right)\right] + R_1$$

(6)

where $R$ is a material parameter, and $R_0$, $Z_0$, and $R_1$ are material constants. These were determined by non-linear regression, as discussed in Sec. III B.

B. IFEM derived properties of 3D printed material

Since the $x$ axis dependence of material properties has been shown to be insignificant, and there are clear
dependencies in the z direction, from hereon the x dependence is neglected and all properties will be assumed to be z dependent only. To more fully map the z-depth dependence of material properties, indentations were conducted on the cross section of a sample with an array of 35 indentations in the z direction to investigate the depth dependence and 3 in the x-directions for averaging (see Figs. 1(b) and 2(a)).

The distance between adjacent rows was 50 μm, the separation between columns was 200 μm, and the distance from the first column to the closest side surface of the sample was 500 μm. The distance from the first indentation to the top surface for each column was around 40 μm. The schematic of the indentation protocol is given in Fig. 2(a). The decrease in the maximum depth of the indentations with respect to depth below the top surface from this array is shown in Fig. 6(a).

In Ref. 28, a number of constitutive models were explored for possible descriptions of a VeroClear 810 ink jet printed material. In this work, we selected a NVEVP based model, which was shown to perform as well or better than other choices. Using the IFEM technique developed in Ref. 28, the spatially varying constitutive properties of VeroClear 810 were determined. This method has benefits over those using direct nanoindentation parameters, since the parameters are intrinsic and can be utilized in any future predictive model based on the same constitutive relationships. Figure 6(b) shows the indentation depth–time curves at selected z-depths [indicated by the crosses in Fig. 6(a)] that were used to determine the material parameters using the IFEM described in Ref. 28.

The basis of the NVEVP model is a VE model, where the viscous stress tensor \( \sigma_i^j(t) \) related to \( g_i \) is computed from
\[ \sigma_i(t) = g_i G_0 \int_0^1 \exp \left( -\frac{t-t_i}{\tau_i} \right) \dot{e} \, dt , \quad (7) \]

where \( t \) is time, \( g_i \) is the relative relaxation modulus and correspondingly, \( \tau_i \) is the relaxation time, \( G_0 \) is the instantaneous modulus, and \( \dot{e} \) is deviatoric strain tensors. If it is assumed that the strain rate does not change significantly (such as in the case of a nanoindentation test), then Eq. (7) can be simplified to

\[ \sigma_i(t) \approx g_i G_0 \dot{e} \int_0^t \exp \left( -\frac{t-t}{\tau_i} \right) \, dt \]
\[ = g_i G_0 \dot{e} \tau_i \left[ 1 - \exp \left( -\frac{t}{\tau_i} \right) \right] . \quad (8) \]

It can be seen from Eq. (8) that the product of \( g_i \) and \( \tau_i \) approximately determines the amplitude of the viscous stress tensor \( \sigma_i(t) \) while \( \tau_i \) shows the effective time range of the change of \( \sigma_i(t) \) is approximately from 0 to \( \tau_i \); after
The material property parameters are fitted with the exponential function given by Eq. (6), by nonlinear regression, and are shown by curves in Figs. 6 and 7. The obtained material parameter results are shown in Table II.

C. Material property evaluation of samples with post-deposition curing

A preliminary experiment to observe the change that may arise with further UV exposure showed that the layer interfaces were no longer visible [Fig. 4(c)]. This suggests that post-curing can lead to the integration of the layers of material, most likely due to cross-linking between layers, creating covalent links, and homogenizing the material. In addition, it demonstrates that further curing over the whole depth of the material may occur, not just at the relatively low modulus upper surface.

Samples with additional UV curing time were indented with a $1 \times 60$ indent map [Fig. 2(c)]. The indentation array was located 1000 µm from its nearest side surface for each test. The distance of the first indentation to the top surface was around 40 µm, and the separation of the two indentations next to each other was 40 µm.

Figure 9 shows the experimentally determined material dependent parameters as a function of the time of exposure. It can be seen that as the duration of exposure lengths, the modulus and hardness increase and correspondingly, the maximum depth of penetration for a given load decreases. This trend is observed for all z-positions. What is also observed is that, although the z-depth dependence is greatly reduced, even at large z-values the modulus and hardness increase, suggesting that curing during manufacture is not close to completion with respect to fully saturated cross-linking. This correlates with the observation that the interfaces at all depths are eliminated with further UV exposure on the cross section [Fig. 4(c)] and that the C=C absorption does not go to zero even at the bottom of the sample (Fig. 5).

TABLE III. Phenomenological constants reflecting the variation in material properties with aging, determined by fitting Eq. (9) to IFEM derived average parameters.

<table>
<thead>
<tr>
<th>Material model</th>
<th>Parameters</th>
<th>$R_0$</th>
<th>$R_1$</th>
<th>$t_0$ (min)</th>
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<td>$E_0$ (GPa)</td>
<td>0.9491</td>
<td>1.4362</td>
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<td></td>
<td>$\tau_1$ (s)</td>
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<td></td>
<td>$\tau_2$ (s)</td>
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<td>288.5935</td>
<td>...</td>
</tr>
<tr>
<td></td>
<td>$\tau_3$ (s)</td>
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<td>8.0771</td>
<td>7.4110</td>
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<td>$\gamma_1$</td>
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<td>$\gamma_3$</td>
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<td>53.0578</td>
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<td></td>
<td>$\beta_1$</td>
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<td>...</td>
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<tr>
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<td>$\beta_2$</td>
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<td>10.2890</td>
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<td>$\beta_3$</td>
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<td></td>
<td>$\sigma_s$ (MPa)</td>
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<tr>
<td></td>
<td>$\eta$ ($\mu$m²/N)</td>
<td>31.4056</td>
<td>7.9816</td>
<td>24.2804</td>
</tr>
</tbody>
</table>

FIG. 12. The change in initial yield stress, $\sigma_s$, and viscoplastic parameter, $\eta$, with post-curing time.

FIG. 13. Schematic diagram showing the process for determining the material properties under various conditions.
Two loads were used for the indentations (Sec. II. B), 50 mN and 75 mN for aging durations of <60 min and >60 min, respectively. One consequence of this difference is that an accurate comparison of aging at short and long times in the context of indentation parameters is not reliable, since there are often load dependent effects that arise.31

Further, the nanoindentation depth versus time curves over the range of \( z \) explored were averaged to obtain mean values of the IFEM derived material parameters (Fig. 10). These average parameters were then plotted as a function of the aging time to observe the dependence on the UV exposure duration. In a pattern similar to that observed in Fig. 8, the material properties tend to vary with aging time, plateauing toward an asymptotic behavior as the duration becomes long (Fig. 11).

Illumination in the UV chamber raises the temperature to 50 °C. To see the effect of this temperature change, control samples were produced, wrapped in the aluminum foil, and placed in the UV test chamber alongside samples open to the UV light. No significant variation with duration of exposure to the heat in the chamber was found (figure not shown).

To better understand the observed time dependence of material properties, a phenomenological description of the \( z \)-averaged behavior was adopted. Since the probability

![Diagram (a) shows the von Mises stress distribution of an indentation with material interface 100 \( \mu \)m away from the indentation center, (b) illustrates the von Mises stress distribution with material gradient and material interface 40 \( \mu \)m away from the indentation center, (c) demonstrates the corresponding distribution of instantaneous modulus, and (d) displays the depth versus time curve obtained by artificial tests for different material interface locations of 0, 20, 40, 60, 80, and 100 \( \mu \)m away from the indentation center, respectively.

FIG. 14.
of absorption per photo-initiator molecule is likely to be constant at the surface, it is reasonable to expect an exponential variation in availability of absorbers over time, and a consequent exponential change in material properties, such that

$$\bar{R} = \bar{R}_0 \left[ 1 - \exp\left( -\frac{t}{t_0} \right) \right] + \bar{R}_1, \quad (9)$$

where $\bar{R}$ is a material parameter determined by IFEM, $\bar{R}_0$, $\bar{R}_1$, and $t_0$ are regression constants, where $t_0$ is a parameter that represents the time it takes for a parameter to decay by $e$. This enables the material parameter variation to be simply characterized with time through $t_0$. The fitted parameters are shown in Table III. Reflecting the increase in modulus with time, Fig. 11(a) shows that the instantaneous modulus determined by IFEM increases with duration of aging. The nonlinear coefficients ($\beta_1$, $\beta_2$, and $\beta_e$) also respond to the additional UV illumination, indicating a change in the degree of non-linearity with curing.

The changes in the viscous part of the material behavior can be observed from the relaxation moduli and their corresponding relaxation times. The relaxation time $\tau_2$ associated with $g_2$ is two orders of magnitude greater than $\tau_1$ and $\tau_3$, suggesting that $g_1$ and $g_3$ can be neglected in comparison to $g_2$ (Fig. 11). The reduction in $g_2$ with curing time indicates a tendency for the material to become less viscous with aging, and less susceptible to processes such as creep. The viscoplastic behavior of the material also varies with aging, with the yielding stress increasing with curing time (Fig. 12). Once again, this indicates a loss of plasticity with aging. However, the increase in viscoplastic parameter $\eta$ (Fig. 12) also suggests that the material becomes more elastoplastic with curing.

**D. Effects of material interfaces and material property gradients**

One aspect that must be resolved before being able to attribute the near surface variation in observed properties to changes in the material behavior is an evaluation of whether performing tests near to the interface between the high modulus EpoFix support resin and the VeroClear 810 resin, in addition to the presence of material property

![Figure 15](image-url)  
**FIG. 15.** The typical material property difference and error between the given value and the value evaluated by IFEM, by using the artificial test strategy, where (a) shows the instantaneous modulus difference, (b) demonstrates the variation of relative relaxation modulus of $g_1$, (c) illustrates the corresponding evaluation error, and (d) shows the first relative relaxation modulus difference.
gradients, may skew the observed results. To address this question, a limited number of fully 3D numerical experiments were performed, which enabled an interface and gradients to be specified. This approach is vastly more computationally intensive than the axisymmetric domain and was only used to determine the degree of bias owing to interfacial and gradient effects.

The 3D model was used to create an “experimental” result with materials of known properties. The test for the IFEM approach was then to use this load-depth information provided by the 3D model and to determine the variance in the determined material properties, the general methodology being shown in Fig. 13. A 3D material subroutine with a linear VE constitutive model was developed using material properties obtained from IFEM. The step change in material properties was implemented in the 3D FE model via a user developed 3D UMAT subroutine [Fig. 14(c)]. The similarity of the 3D result to an axisymmetric model is illustrated by Fig. 14, where as can be seen from Fig. 14(a), when the indentation center is 100 μm away from the interface, the stress distribution is almost axisymmetric and when the indentation center is 40 μm away from the interface, the stress distribution is slightly away from axisymmetric distribution [Fig. 14(b)]. Although the material property gradient, material interface, and a step change in property at the interface are involved in the model, the output of FE modeling is still close to be axisymmetric, depending on the distance of indentation location to the material interface.

Figure 15 shows the percentage variation in key material properties as the numerical indentation experiment is moved toward the interface. For example, a distance of 0 μm would reflect a 3D FE model of an indentation exactly on the interface between the two materials, from which the axisymmetric IFEM based model would extract material data (which assumes a homogenous VeroClear 810 material distribution). It can be seen that there is a 5–10% error at 20 μm from the interface, beyond which the error increases as the interface is approached. This suggests that at distances greater than ~20 μm, errors below 5% can be expected, and such discrepancies are significantly below the experimental variations observed near to the surface. Therefore the assumptions on which the IFEM model is based (axisymmetry, small gradients within) can be considered safe, and the influence of the stiffer material can be considered negligible for distances greater than 20 μm from the interface. Noting that this is only correct for these materials and test conditions.

IV. CONCLUSIONS

A 3D ink jet printed part was examined for spatial and temporal variations, with material parameters derived by using IFEM in combination with indentation, and then fitting phenomenological relations to obtain parametric dependencies. This showed a clear z dependence. This z dependence was reduced by further exposure to UV light, which acts to homogenize the material and eliminate the strong gradients in the material properties. The IFEM derived parameters and the phenomenological relations that empirically describe the variation in z and with aging, can be used to predict intra-part properties and how the behavior will evolve with exposure to aging conditions.

ACKNOWLEDGMENTS

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